Dc motor :

void setup()

{

pinMode(6,OUTPUT );

pinMode(5, OUTPUT);

pinMode(4, OUTPUT);

pinMode(3, OUTPUT);

}

void loop(){

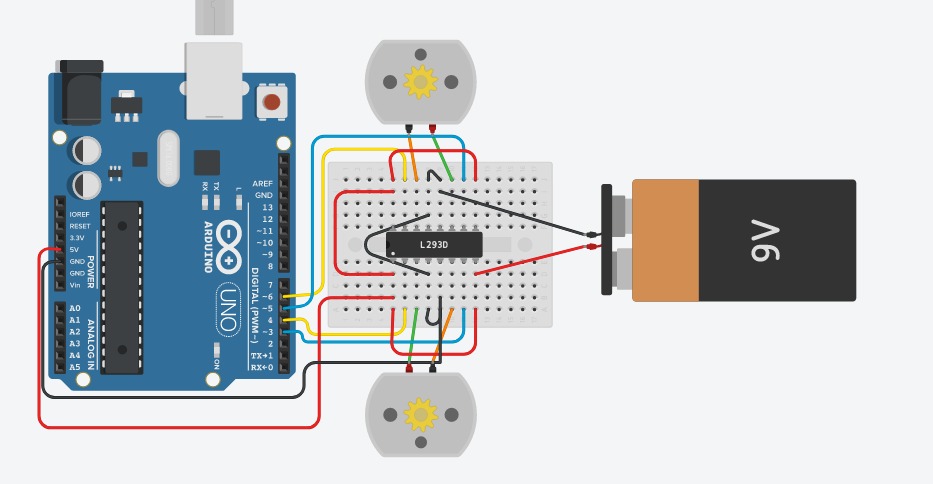
digitalWrite(6, HIGH);

digitalWrite(5, LOW);

digitalWrite(4, HIGH);

digitalWrite(3, LOW);

delay(1000);

}